IN THE SPECIFICATION:

Please amend page 3, third full paragraph bridging page 4 to read as follows:

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1A is a elevational view of device for alignment of a vehicle A.

Figure 1B shows the alignment device shown in Fig. 1A viewed from above.

Figure 2A shows a measurement device comprising a measurement frame fitted on an alignment table. Centering of the measurement device in compliance with the center line of the vehicle is shown, and, as shown in the figure, support arms in accordance with the invention are fitted between the measurement frame and the vehicle.

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Figure 2B shows the apparatus in accordance with the invention viewed from above, four support arms being arranged to be coupled with the vehicle to be aligned.

Figure 2C is a sectional view taken along the line I-I in Fig. 2B.

Figure 2D illustrates the apparatus arrangement shown in Fig. 2C as viewed in the direction of the arrow k_1.

Figure 3A shows a measurement system in accordance wiht the ivention in which a

measurement head 65 is connected to a measurement arm 40 though an articulation 41 and arms 42 and 43. The figure illustrates the measurement device arrangement in accordance with the invention.

Figure 3B is an exploded view of the measurement apparatus of the invention connected to the measurement arm.

Figure 3C shows holes situated in an end face 44b of a sleeve 44, a ball/balls being positioned in said holes in locking positions.

Figure 3D is a cross-sectional view of the arm 42. It shows holes situated with an angular spacing of 90°, balls being positioned in said holes in a locking situation.

B2

Figure 3E is a cross-sectional view of the arm 42. It shows holes on a opposite side of arm 42 than those of Figure 3D, situated with an angular spacing of 90°, balls being positioned in said holes in a locking situation.

Figure 4 illustrates measurements carried out by means of the apparatus in accordance with the invention. The measurements are denoted with reference numerals 1, 2 ... and 5.

Figure 5A-5E show on an enlarged scale the measurement points shown by numeral 1-5 in Fig. 4.

Marked-up version of page 3, third full paragraph bridging page 4 , as amended.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1A is a elevational view of device for alignment of a vehicle A.

Figure 1B shows the alignment device shown in Fig. 1A viewed from above.

Figure 2A shows a measurement device comprising a measurement frame fitted on an alignment table. Centering [Centring] of the measurement device in compliance with the center [centre] line of the vehicle is shown, and, as shown in the figure, support arms in accordance with the invention are fitted between the measurement frame and the vehicle.

Figure 2B shows the apparatus in accordance with the invention viewed from above, four support arms being arranged to be coupled with the vehicle to be aligned.

Figure 2C is a sectional view taken along the line I-I in Fig. 2B.

Figure 2D illustrates the apparatus arrangement shown in Fig. 2C as viewed in the direction of the arrow k_1.

Figure 3A shows a measurement system in accordance with the invention in which a measurement head 65 is connected to a measurement arm 40 though an articulation 41 and arms

42 and 43. The figure illustrates the measurement device arrangement in accordance with the invention.

Figure 3B is an exploded view of the measurement apparatus of the invention connected to the measurement arm.

Figure 3C shows holes situated in an end face 44b of a sleeve 44, a ball/balls being positioned in said holes in locking positions.

Figure 3D is a cross-sectional view of the arm 42. It shows holes situated with an angular spacing of 90°, balls being positioned in said holes in a locking situation.

Figure 3E is a cross-sectional view of the arm 42. It shows holes on a opposite side of arm 42 than those of Figure 3D, situated with an angular spacing of 90°, balls being positioned in said holes in a locking situation.

Figure 4 illustrates measurements carried out by means of the apparatus in accordance with the invention. The measurements are denoted with reference numerals 1, 2 ... and 5.

Figure 5A-5E show on an enlarged scale the measurement points shown by numeral 1-5 in Fig. 4.

Please amend page 7, first full paragraph , to read as follows:

Fig. 2D illustrates the apparatus viewed in the direction of the arrow K_1 in Fig. 2C, i.e. from above. The transverse guide $16a_1$, $16a_2$,$16a_3$... comprises a plate part 16d situated at its ends perpendicularly to its bridge beam 16c, which plate part 16d includes a number of bearings. 16b, which are fitted in said plate part 16d and arranged to travel along with the plate part in longitudinal guide groove U_3 in the longitudinal guide $15a_1$.

Marked-up version of page 7, first full paragraph , as amended.

Fig. 2D illustrates the apparatus viewed in the direction of the arrow K_1 in Fig. 2C, i.e. from above. The transverse guide $16a_1$, $16a_2$,$\underline{16a_3}$... comprises a plate part 16d situated at its ends perpendicularly to its bridge beam 16c, which plate part 16d includes a number of bearings. 16b, which are fitted in said plate part 16d and arranged to travel along with the plate part in longitudinal guide groove U_3 in the longitudinal guide $15a_1$.

Please amend page 10, first full paragraph , to read as follows:

As shown in Fig. 3B, the second arm part 43 is placed in the inner space D of the first arm part 42 as shown by the arrow L, such that springs $61a_1$, $61a_2$ and balls $62a_1$, $62a_2$ ... situated in holes $60a_{1'}$, $60a_1$; $60a_{2'}$, $60a_2$... at the end of the second arm part 42 will be cooperative with the holes $55a_1'$, $55a_1$, $55a_2'$, $55a_2$ ... or $56a_1'$, $56a_1$... of the first arm part 42. The springs $61a_1$ and $61a_2$ and the balls $62a_1$, $62a_2$ ... are cooperative with the holes $56a_1'$, $56a_1$, $56a_2'$, $56a_2$ or with the holes $55a_1'$, $55a_1$, $55a_2'$, $55a_2$ at either end of the first arm part 42, i.e. the first arm part can be placed by a linear movement L_1 to alternative length positions with respect to the first arm part 42. The balls $62a_1$, $62a_2$, $62a_3$, $62a_4$ ... are preferably situated on the opposite sides of the arm 43, in their holes $56a_1$, $56a_{1'}$, into which the springs $61a_1$, $61a_2$, ... are placed.

Marked-up version of page 10, first full paragraph , as amended.

As shown in Fig. 3B, the second arm part 43 is placed in the inner space D of the first arm part 42 as shown by the arrow L, such that springs $61a_1$, $61a_2$ and balls $62a_1$, $62a_2$ ... situated in holes $60a_1$', $60a_1$; $60a_2$', $60a_2$... at the end of the second arm part 42 will be cooperative with the holes $55a_1$', $55a_1$, $55a_2$', $55a_2$ ... or $56a_1$', $56a_1$... of the first arm part 42. The springs $61a_1$ and $61a_2$ and the balls $62a_1$, $62a_2$ ... are cooperative with the holes $56a_1$', $56a_1$, $56a_2$', $56a_2$ or with the holes $55a_1$', $55a_1$, $55a_2$', $55a_2$ at either end of the first arm part 42, i.e. the first arm part can be placed by a linear movement L_1 to alternative length positions with respect to the first arm part 42. The balls $62a_1$, $62a_2$, $62a_3$, $62a_4$ ... are preferably situated on the opposite sides of the arm 43, in their holes $56a_1$, $56a_1$', into which the springs $61a_1$, $61a_2$, ... are placed.

Please amend page 11, first full paragraph , to read as follows:

As shown in Fig. 3C, the holes $45a_1$, $45a_2$, $45a_3$, $45a_4$ ... are situated with an angular spacing of 45° on the end face 44b of the sleeve 44. The balls $46a_1$, $46a_2$ are positioned in the holes $45a_1$, $45a_2$,$45a_3$... in a locking situation.

Marked-up version of page 11, first full paragraph , as amended.

As shown in Fig. 3C, the holes $45a_1$, $45a_2$, $45a_3$, $45a_4$ ... are situated with an angular spacing of 45° on the end face 44b of the sleeve 44. The balls $46a_1$, $46a_2$ are positioned in the holes $45a_1$, $45a_2$,$45a_3$... in a locking situation.

Please amend page 12, first full paragraph , to read as follows:

Fig. 3D shows the holes $56a_1$, $56a_2$, $56a_3$, $56a_4$ of the arm 42 into which the balls $62a_1$, $62a_2$... are pressed by the springs $61a_1$, $61a_2$ in any given locking situation. The holes are provided with an angular spacing of 90°, thereby enabling the arm 43 to have eight different locking positions when turning it around its longitudinal axis X_{30}.

Marked-up version of page 12, first full paragraph , as amended.

Fig. 3D shows the holes $56a_1$, $56a_2$, $\underline{56a_3}$, $\underline{56a_4}$ of the arm 42 into which the balls $62a_1$, $62a_2$... are pressed by the springs $61a_1$, $61a_2$ in any given locking situation. The holes are provided with an angular spacing of 90°, thereby enabling the arm 43 to have eight different locking positions when turning it around its longitudinal axis X_{30}.